



심사결과 통지서

신청인	사업장명 (주)KITO	사업장관리번호 2010E110010
	사업자등록번호 010-E1-10010	대표자 성명 KITO YOSHIO
	소재지 2000, Tsujijarai, Showa-Cho, Nakakoma-Gun, Yamanashi, Japan	

안전인증대상기계·기구명	호이스트		
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형식(규격)	KMS-ER2-010	용량(등급)	1 ton
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「산업안전보건법」 제34조 및 같은 법 시행규칙 제58조의4제4항에 따라 실시한

예비심사

서면심사

기술능력 및 생산체계 심사

결과가 적 합 함을 통지합니다.
 부적합

개별 제품심사

형식별 제품심사

2012년 06월 20일

인증심사원

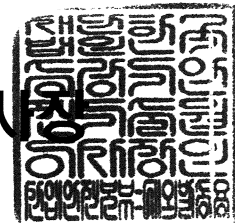
최 창 일

(체량인)

오 태 화

(의명)

한국승강기안전기술원 이사





제 CA-2012-0027 호

안 전 인 증 서

(사업장명) (주)KITO

(소재지) 2000, Tsujiarai, Showa-Cho, Nakakoma-Gun, Yamanashi, Japan

위 사업장에서 제조하는 아래의 품목이 「산업안전보건법」 제34조 및 같은 법 시행규칙 제58조의4제4항에 따른 안전인증 심사결과 안전·보건기준에 적합하므로 안전인증표시의 사용을 인증합니다.

_____	품 명 : 호이스트	_____
_____	형식(용량): KMS-ER2-010(1 ton)	_____
_____	인증번호 : 12-CA4AC-0027	_____
_____	인증기준 : 위험기계·기구 의무안전인증기준 (고용노동부고시 제2011-39호)	_____
_____	인증조건 : 산업안전보건법 "제34조 준수"	_____

2012년 11월 30일

한국승강기안전기술원 이사장



【별지 제4호서식】

동 일 형 식 일 람 표

사업장명	KITO CORP.		개정일자 및 번호	2012.05.10	인증번호	
형식 및 모델번호		동일형식 항목 및 내역				
형식번호	모델번호	동일형식 항목1	동일형식 항목2	동일형식 항목3	동일형식 항목4	
KMS-ER2-010	KITO-ER2-010S	Lift max 30m	권상모타 1.8kW	횡행모타 없음	Trolley고정형	
	KITO-ER2-010IS				Trolley 있음	
	KITO-ER2SP010S				권상모타 1.8kW	Trolley 있음
	KITO-ER2SP010IS		권상모타 1.8kW	Trolley + 수동체인		
	KITO-ER2SG010S		권상모타 1.8kW	권상모타 1.8kW	횡행모터 0.4kW .S : 24m/min .L: 12m/min .IS:24/4m/min .IL:12/2m/min	전기Trolley 결합 type
	KITO-ER2SG010IS					
	KITO-ER2M010S-S					
	KITO-ER2M010S-L					
	KITO-ER2M010S-IS					
	KITO-ER2M010S-IL					
	KITO-ER2M010IS-S					
	KITO-ER2M010IS-L					
	KITO-ER2M010IS-IS					
	KITO-ER2M010IS-IL					
	KITO-C-ER2M010S-S		권상모타 1.8kW	전기Trolley 결합 Clean type		
	KITO-C-ER2M010S-L					
	KITO-C-ER2M010S-IS					
	KITO-C-ER2M010S-IL					
	KITO-C-ER2M010IS-S		권상모타 1.8kW	전기Trolley 결합 Clean type		
	KITO-C-ER2M010IS-L					
KITO-C-ER2M010IS-IS						
KITO-C-ER2M010IS-IL						



제 2012-BJ-0009 호



안 전 인 증 서

정호엔지니어링

경기도 광명시 노온사동 440-5

위 사업장에서 제조하는 아래의 품목이 산업안전보건법 제34조 및 같은 법 시행규칙 제58조의4제4항에 따른 안전인증 심사 결과 안전·보건기준에 적합하므로 안전인증표시의 사용을 인증합니다.

품 목

양중기용 과부하방지장치

형식·모델/용량·등급/인증번호

형식·모델
JDL-100

용량·등급
J-2

인증번호
12-AV2BJ-0009

인 증 기 준

방호장치 의무안전인증 고시(고용노동부고시 제2010-36호)

인 증 조 건

아래 주소에서 생산되는 제품에 한함.

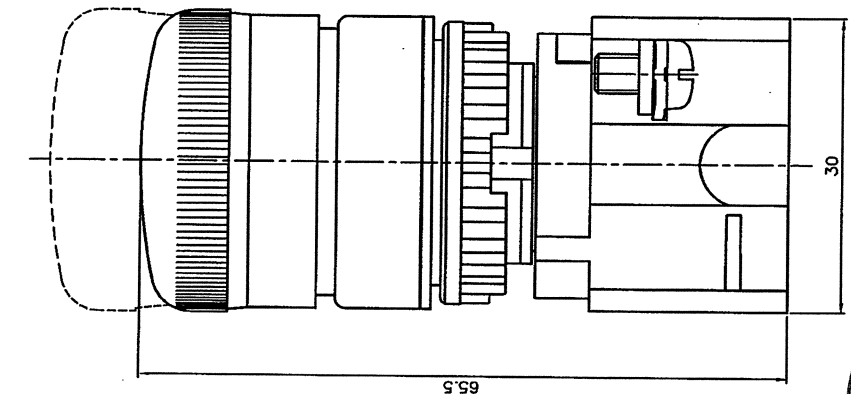
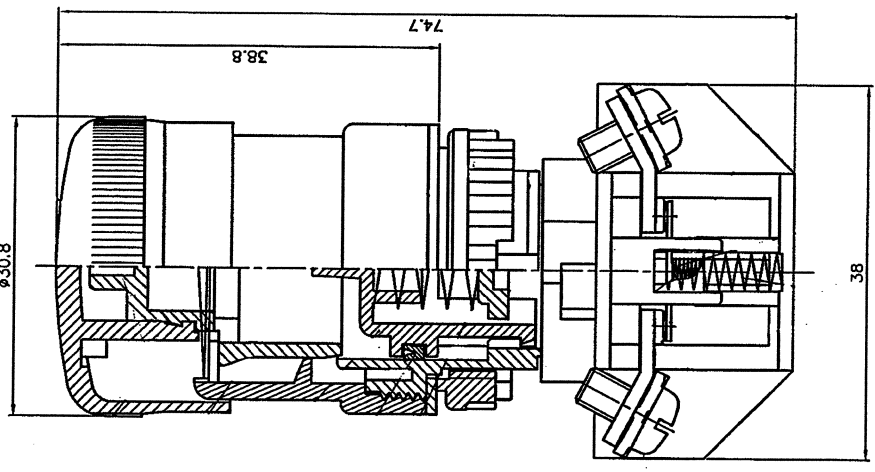
정호엔지니어링, 경기도 광명시 노온사동 440-5

2012년 06월 11일

한국산업안전보건공단 이사장



F E D C B A



2012 .06

한글기술연구소

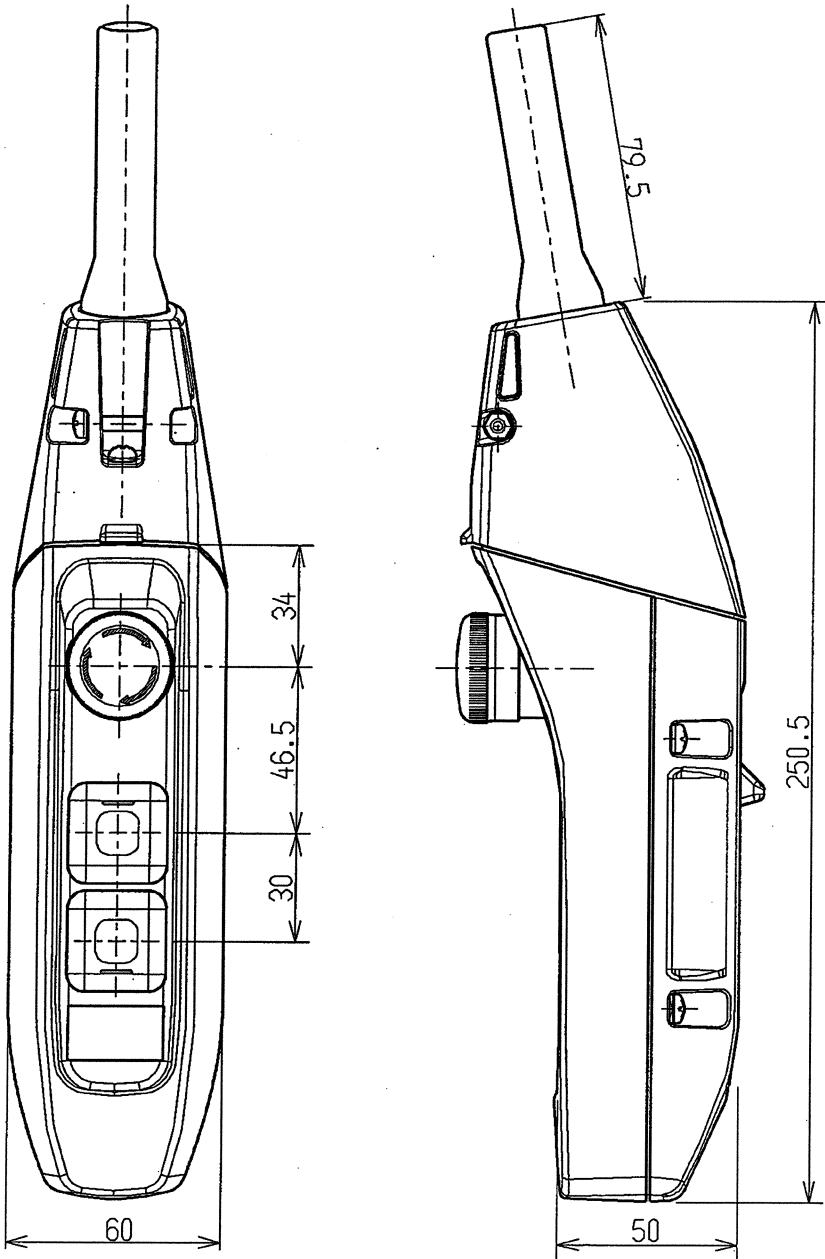
기 변 심

天得科技股份有限公司
TEND-TECHNOLOGY CO.,LTD.

圖號	T2-BKH
品名	T2 BKH 連鎖開關
材質	表面處理
單位	mm
比例	2:1
投影法	第一角
視孔數	0
繪圖	張科錄 95.05.24 姜宗達
校對	研發部 95.05.24 周啟祥
核准	研發部 95.05.24 韓健丞
標準材質	60.1~300mm: ±0.5
品保	品保部 95.05.24 林建丞
最新修正	
前次修正	

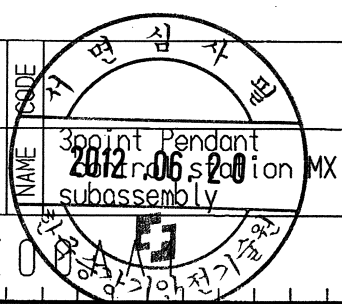
圖號: A

Revision	Incidence	Description	Date	Charge	Approved
1					

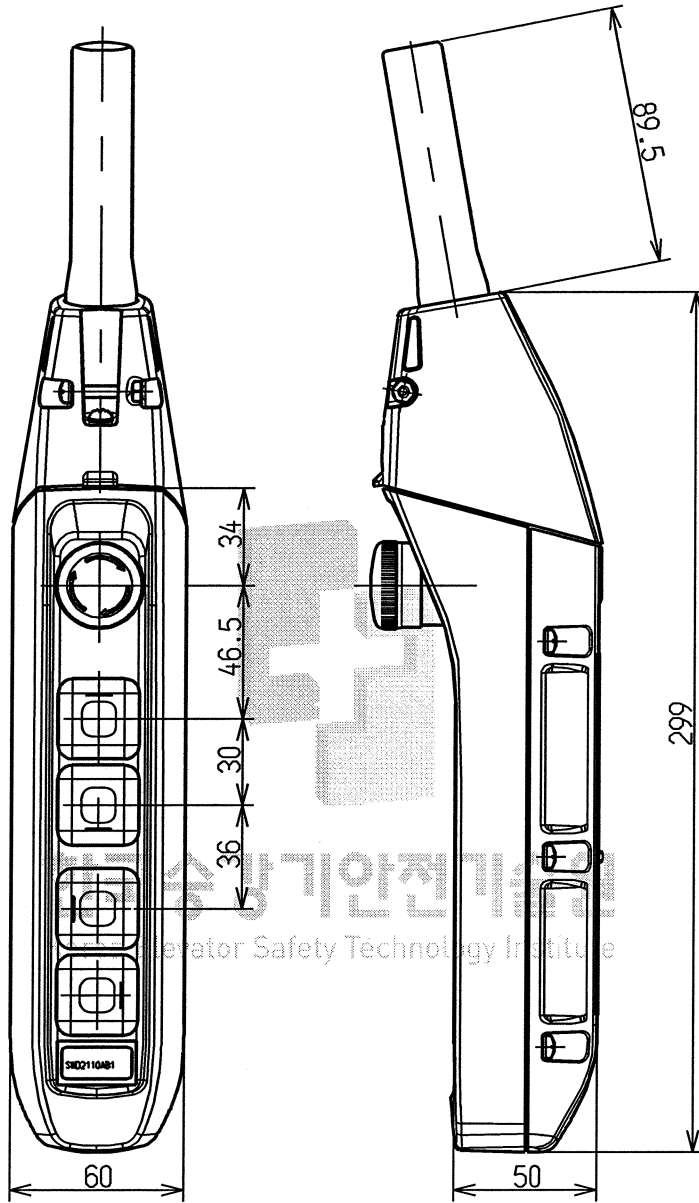


6
5
4
3
2
1

NOTE						MATERIAL		NAME	
APPROVED	ISHIKAWA	CHECKED	FURIYA	DESIGNED	KOBAYASHI	DRAWN	KOBAYASHI	DWG. NO.	SWD2X0
Date issued	08.02.08		08.02.08		08.02.08		08.02.08	SCALE	-



Revision	Incidence	Description	Date	Charge	Approved

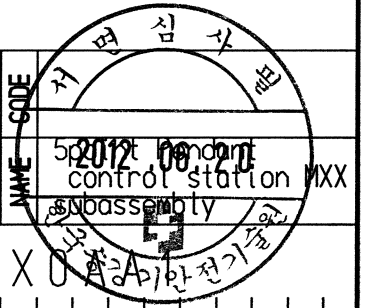


The lifting and lowering push buttons are marked with \updownarrow for single speed or $\blacktriangle\blacktriangledown$ for dual speed.
 The traveling push buttons are marked with E W or N S depending on the installed direction.

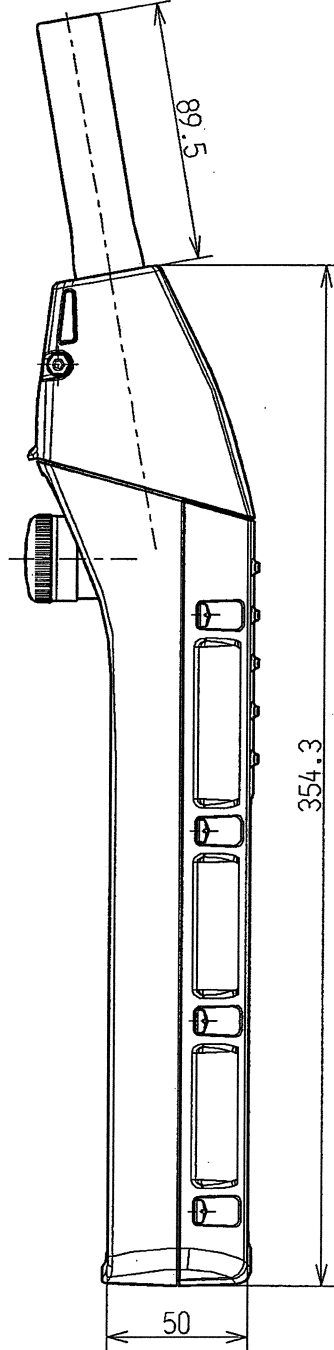
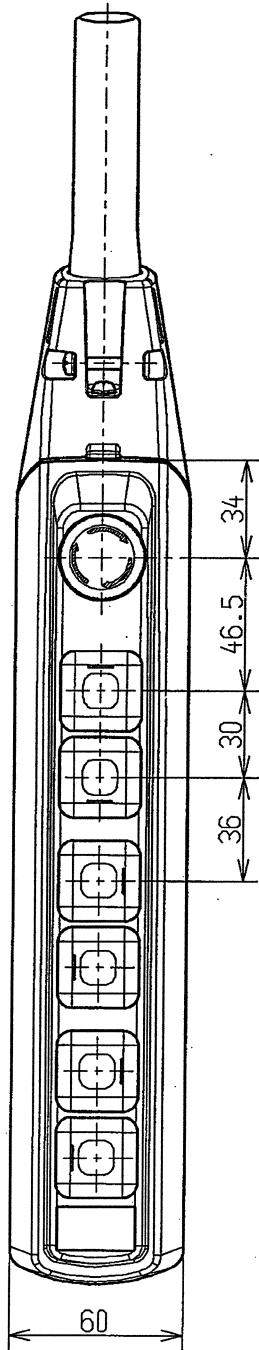
⑥
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NOTE

APPROVED	H.FURIYA	CHECKED	T.HATANO	DESIGNED	KOBAYASHI	DRAWN	KOBAYASHI	SCALE	-	DWG. NO.	SWD2XX0	MATERIAL		MATERIAL		MATERIAL		MATERIAL	
Date issued	09.04.21		09.04.21		09.04.21		09.04.21												



Revision	Incidence	Description	Date	Charge	Approved



E
W
S
N

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B
C
D
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F
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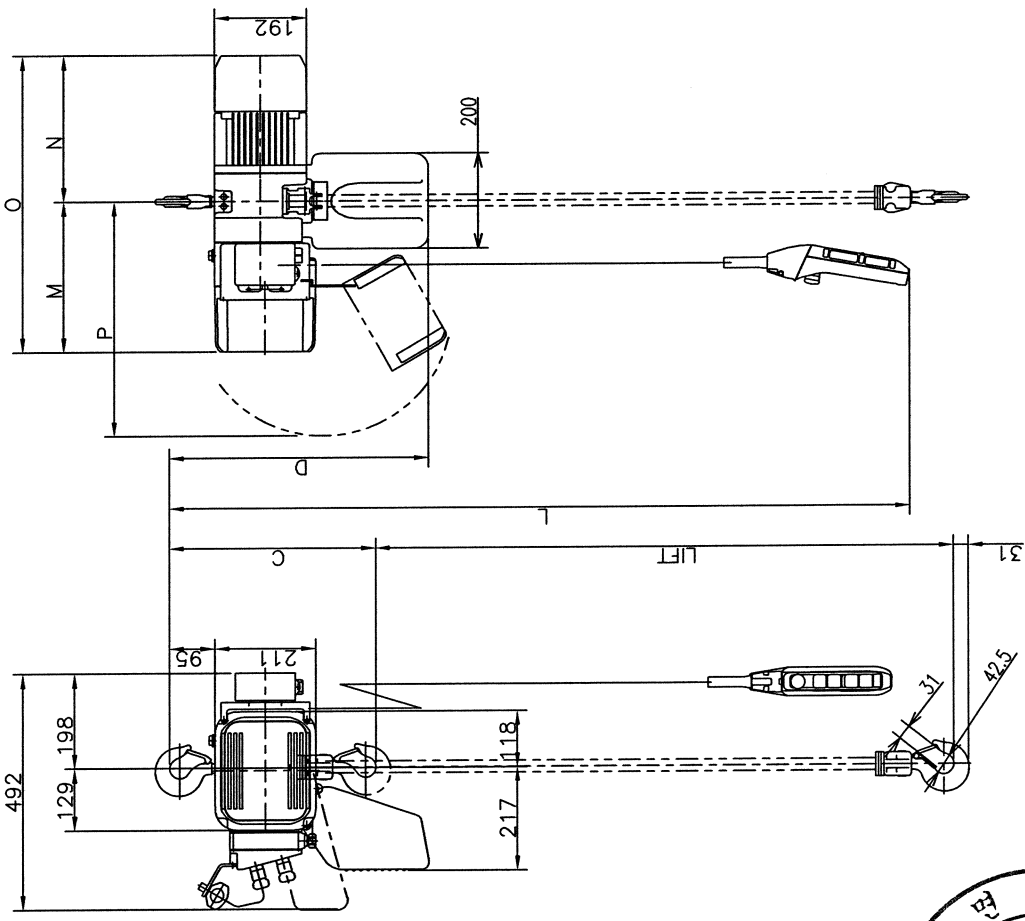
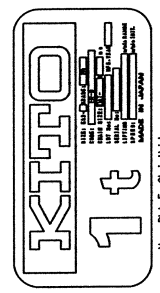
APPROVED		CHECKED		DESIGNED		DRAWN		SCALE		DWG. NO.		NOS./UNIT MATERIAL		NAME CODE	
ISHIKAWA		FURIYA		KOBAYASHI		KOBAYASHI		-		S		WD2XX		2012.06.20 control station subassembly XXXX KTO	
Date issued		08.02.08		08.02.08		08.02.08		08.02.08		-		-		-	

1 2 3 4 5 6 7 8 9

형식번호: KMS-ER2-010
 Model number.
 KITO-ER2-010S
 KITO-ER2-010IS

基本仕様 Nominal Capacity	ER2-D 1t
チェーンサイズ Chain size	3m(max 30m) φ7.7 x 1
レール下面より フックまでの最小距離 Min. Headroom	470mm
相数・電圧 Phase・Voltage	3φ 220(208)V 60Hz 380, 440V 60Hz
Motor Output Duty Rating	IS 1.8kW x 4P S 1.8kW x 4P
巻上速度 Lifting Speed	IS 8.2/1.4 m/min S 8.5 m/min
オンスローモード長さ Push Button Lead	2.5 m(max 29.5m)
ケーブル長さ Length of Power Supply Cable	550mm(max 1000)
レール下面よりチェーン パケットまでの寸法 Chain Carriage Distance from Bottom of Beam	58~127mm
質量 Mass	約 46kg
塗装色 Painting Color	ブルー 7.5YR7/14 ブラック 7.5YR7/14

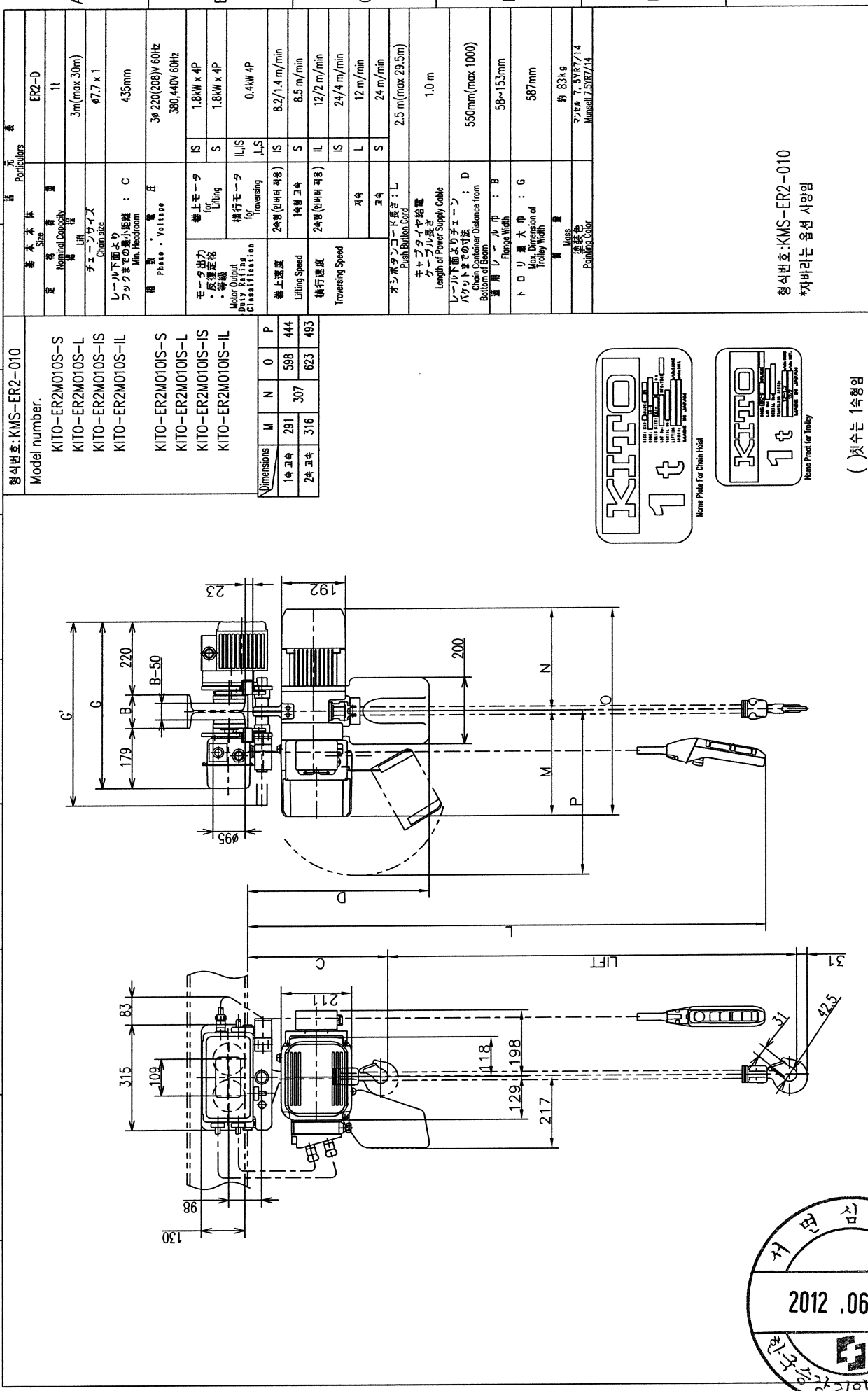
寸法 Dimensions	M 291 N 307 O 444 P 316 Q 307 R 623 S 493
巻上速度 Lifting Speed	IS 8.2/1.4 m/min S 8.5 m/min
オンスローモード長さ Push Button Lead	2.5 m(max 29.5m)
ケーブル長さ Length of Power Supply Cable	550mm(max 1000)
レール下面よりチェーン パケットまでの寸法 Chain Carriage Distance from Bottom of Beam	58~127mm
質量 Mass	約 46kg
塗装色 Painting Color	ブルー 7.5YR7/14 ブラック 7.5YR7/14



名称 TITLE	1t ER2 SERIES ELECTRIC CHAIN HOIST STANDARD	
製造番号 CODE	ER2	
図番 DWG. NO.	KMS-ER2-010-001	
訂正回数 REV.		
承認 APPROVED	設計 DESIGNED	製図 DRAWN
検査 CHECKED		
株式会社 KITO CORP.		
承認 APPROVED	製図 DRAWN	承認 APPROVED
年 月 日 DATE		
内容 CONTENTS		
改訂 REV.	数 QTY	

様式 025P-19 三角法 単位 : mm

1 2 3 4 5 6 7 8 9



형식번호: KMS-ER2-010
Model number.

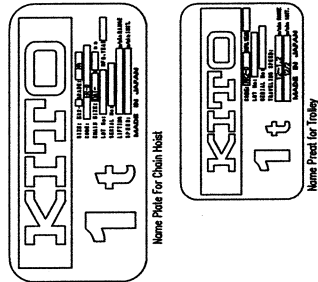
KITO-ER2M010S-S	M	N	O	P
KITO-ER2M010S-L	291	307	598	444
KITO-ER2M010S-IS	316	623	493	
KITO-ER2M010S-IL				

Motor Output
출력
Capacity
능력
Classification
구분

1st 고속	598	444
2nd 고속	623	493

상체 Body	ER2-D	
정격 용량 Nominal Capacity	1t	
체인 길이 Chain size	3m(max 30m)	
체인 크기 Chain size	Ø7.7 x 1	
레일 하단에서의 최소 거리 Min. Headroom	435mm	
용량 Capacity	3φ 220(208)V 60Hz 380,440V 60Hz	
모터 출력 출력 Capacity 능력 Classification 구분	IS	1.8kW x 4P
	S	1.8kW x 4P
	IL, IS	0.4kW 4P
상승 속도 Lifting Speed	IS	8.2/1.4 m/min
상승 속도 Lifting Speed	S	8.5 m/min
横行 속도 Traversing Speed	IL	12/2 m/min
横行 속도 Traversing Speed	IS	24/4 m/min
横行 속도 Traversing Speed	L	12 m/min
横行 속도 Traversing Speed	S	24 m/min
오일 포트 위치 Oil Port Position	L	2.5 m(max 29.5m)
케이블 길이 Cable Length		1.0 m
레일 하단에서의 최소 거리 Min. Headroom		550mm(max 1000)
레일 폭 Rail Width		56~153mm
트럭 폭 Trolley Width		587mm
중량 Weight		약 83kg
도색 Painting Color		파우더 7.5YR7/14 Munsell 7.5YR7/14

형식번호: KMS-ER2-010
차지바리는 옵션 사양임

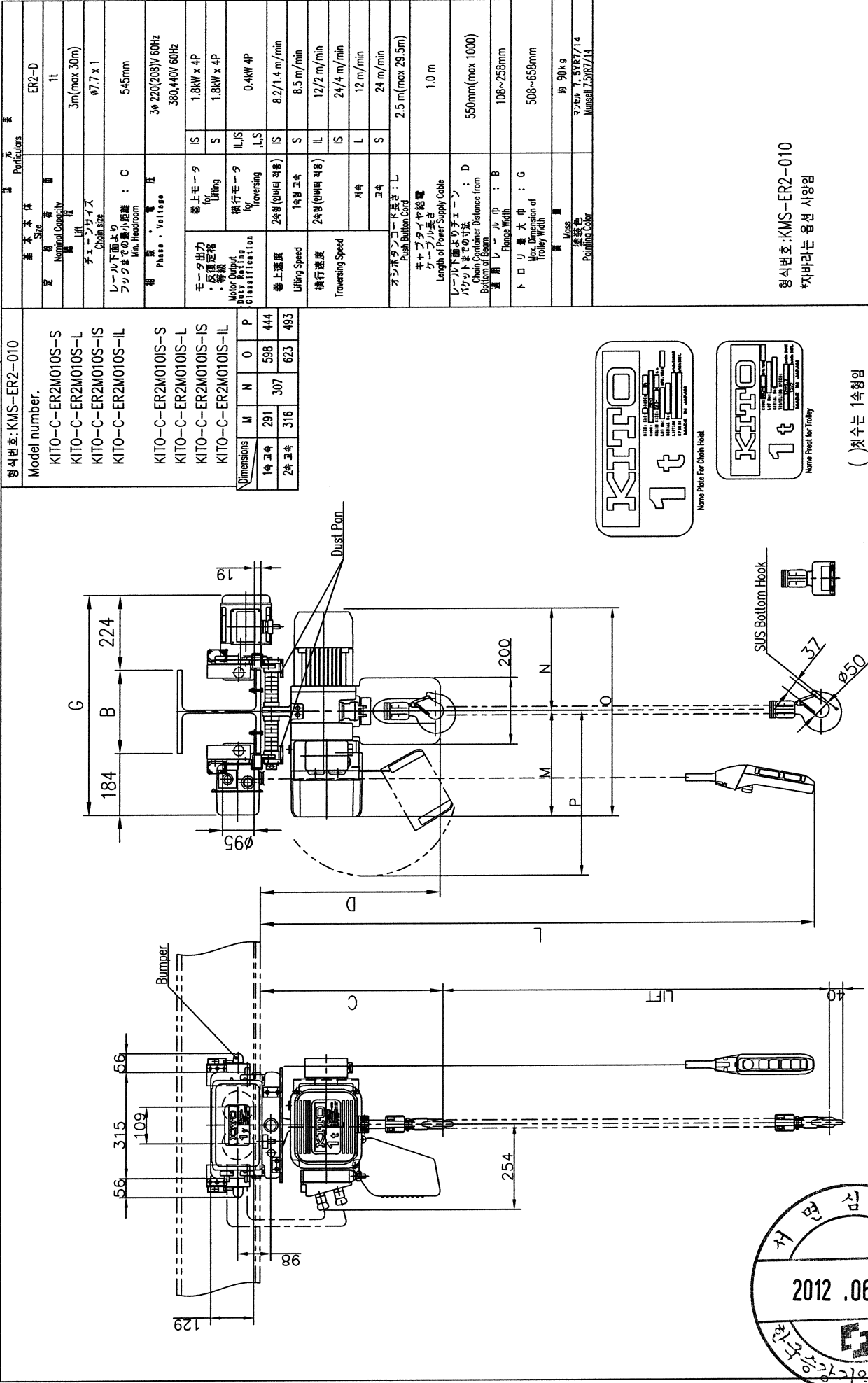


() 외수는 1속형임

승인 APPROVED	검토 CHECKED	설계 DESIGNED	제출 DRAWN	명칭 TITLE	1t ER2M SERIES ELECTRIC CHAIN HOIST WITH MOTORIZED TROLLEY
년 YEAR	월 MONTH	일 DAY	번호 NO.	도면 DRAWING	ER2-M
년 YEAR	월 MONTH	일 DAY	번호 NO.	도면 DRAWING	KMS-ER2-010-004
REV.	QTY	CONTENTS			



1 2 3 4 5 6 7 8 9



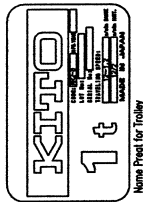
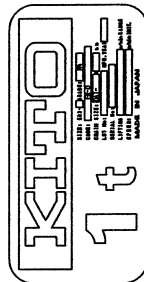
형식번호: KMS-ER2-010
Model number.

KITO-C-ER2M010S-S	M	N	O	P
KITO-C-ER2M010S-L	291	307	598	444
KITO-C-ER2M010S-IS	316	623	623	493
KITO-C-ER2M010S-IL				

Dimensions

1속 고속	2속 고속
291	316
307	623
598	623
444	493

基本仕様 Nominal Capacity	基本仕様 ER2-D
チェーンサイズ Chain Size	1t
レール下面よりフックまでの最小距離 Min. Headroom	3m(max 30m) φ7.7 x 1 545mm
モーター出力・区別定格 Motor Output Classification	3φ 220(208)V 60Hz 380/440V 60Hz
巻上速度 Lifting Speed	1.8kW x 4P 1.8kW x 4P 0.4kW 4P
横行速度 Traversing Speed	2속형 (인버터 적용) IS 8.2/1.4 m/min 1속형 고속 S 8.5 m/min 2속형 (인버터 적용) IS 12/2 m/min IL 24/4 m/min 저속 L 12 m/min 고속 S 24 m/min
オンボルトコンクリート埋込み Flush Bolt-in Cast	2.5 m(max 29.5m)
ケーブル長さ Length of Power Supply Cable	1.0 m
レール下面よりチェーン・ハンガーまでの寸法 Chain Contactor Distances from Bottom of Beam	550mm(max 1000)
巻上距離 Rising Distance	108~258mm
トロリ溝大巾 Max. Dimension of Hoist Width	508~658mm
質量 Mass	約 90kg
塗装色 Painting Color	カラー 7.5VR7/14 Munsell 7.5R7/14



형식번호: KMS-ER2-010
차지버리는 용선 사양임

(寸수는 1속형임)

名 称 TITLE	1t ER2M SERIES ELECTRIC CHAIN HOIST(CLEAN) WITH MOTORIZED TROLLEY		
製造番号 CODE	ER2S-MC		
図番 DWG. NO.	KMS-ER2-010-005		
尺 度 SCALE	実尺 1:1		
承認 APPROVED	設計 DESIGNED	製 図 DRAWN	検 査 CHECKED
年 月 日 DATE	年 月 日 DATE	年 月 日 DATE	年 月 日 DATE
訂 数 QTY	内 容 要 素 CONTENTS		
製 造 社 会 社 KITO CORP.	株 式 会 社 KITO CORP.		



단위 : mm
比例尺 : 1:1

LOAD SUMMARY 1 – INVERTER사양(고속)

*POWER SOURCE : AC 3Φ 220(208)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	1.8KW x 4P	0.4KW x 4P	
FULL LOAD CURRENT	11.2 (A)	3 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상과 횡행시 : HOISTING + TRAVERSING + CONTROL CIRCUIT = 16.2 A

*** PEAK 전류값 ***

K= NOMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 16.2 * 1.25 = 20.25 A

*POWER SOURCE : AC 3Φ 380(440)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	1.8KW x 4P	0.4KW x 4P	
FULL LOAD CURRENT	5.1 (A)	2.5 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상과 횡행시 : HOISTING + TRAVERSING + CONTROL CIRCUIT = 9.6 A

*** PEAK 전류값 ***

K= NOMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 9.6 * 1.25 = 12 A



LOAD SUMMARY 2 – INVERTER사양(고속)

*POWER SOURCE : AC 3Φ 220(208)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	1.8KW x 4P	-	
FULL LOAD CURRENT	11.2 (A)	0 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상시 : HOISTING + CONTROL CIRCUIT = 13.2 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 13.2 * 1.25 = 16.5 A

*POWER SOURCE : AC 3Φ 380(440)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	1.8KW x 4P	-	
FULL LOAD CURRENT	5.1 (A)	0 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상시 : HOISTING + CONTROL CIRCUIT = 7.1 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 7.1 * 1.25 = 8.875 A



LOAD SUMMARY 3 – INVERTER사양(저속)

*POWER SOURCE : AC 3Φ 220(208)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	0.9KW x 4P	0.4KW x 4P	
FULL LOAD CURRENT	5.7 (A)	3 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상과 횡행시 : HOISTING + TRAVERSING + CONTROL CIRCUIT = 10.7 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 10.7 * 1.25 = 13.375 A

*POWER SOURCE : AC 3Φ 380(440)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	0.9KW x 4P	0.4KW x 4P	
FULL LOAD CURRENT	3.6 (A)	2.5 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상과 횡행시 : HOISTING + TRAVERSING + CONTROL CIRCUIT = 8.1 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 8.1 * 1.25 = 10.125 A



LOAD SUMMARY 4 – INVERTER사양(저속)

*POWER SOURCE : AC 3Φ 220(208)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	0.9KW x 4P	-	
FULL LOAD CURRENT	5.7 (A)	0 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상시 : HOISTING + CONTROL CIRCUIT = 7.7 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 7.7 * 1.25 = 9.625 A

*POWER SOURCE : AC 3Φ 380(440)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	0.9KW x 4P	-	
FULL LOAD CURRENT	3.6 (A)	0 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상시 : HOISTING + CONTROL CIRCUIT = 5.6 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 5.6 * 1.25 = 7 A



LOAD SUMMARY 5 - 1속고속형사양

*POWER SOURCE : AC 3Φ 220(208)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	1.8KW x 4P	0.4KW x 4P	
FULL LOAD CURRENT	8.4 (A)	3 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상과 횡행시 : HOISTING + TRAVERSING + CONTROL CIRCUIT = 13.4 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 13.4 * 1.25 = 16.75 A

*POWER SOURCE : AC 3Φ 380(440)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	1.8KW x 4P	0.4KW x 4P	
FULL LOAD CURRENT	4.6 (A)	2.2 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상과 횡행시 : HOISTING + TRAVERSING + CONTROL CIRCUIT = 8.8 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 8.8 * 1.25 = 11 A



LOAD SUMMARY 6 - 1속고속형사양

*POWER SOURCE : AC 3Φ 220(208)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	1.8KW x 4P	-	
FULL LOAD CURRENT	8.4 (A)	0 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상시 : HOISTING + CONTROL CIRCUIT = 10.4 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 10.4 * 1.25 = 13 A

*POWER SOURCE : AC 3Φ 380(440)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	1.8KW x 4P	-	
FULL LOAD CURRENT	4.6 (A)	0 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상시 : HOISTING + CONTROL CIRCUIT = 6.6 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 6.6 * 1.25 = 8.25 A



LOAD SUMMARY 7 - 1속저속형사양

*POWER SOURCE : AC 3Φ 220(208)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	0.9KW x 4P	0.4KW x 4P	
FULL LOAD CURRENT	4.7 (A)	3 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상과 횡행시 : HOISTING + TRAVERSING + CONTROL CIRCUIT = 9.7 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 9.7 * 1.25 = 12.125 A

*POWER SOURCE : AC 3Φ 380(440)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	0.9KW x 4P	0.4KW x 4P	
FULL LOAD CURRENT	2.6 (A)	2.2 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상과 횡행시 : HOISTING + TRAVERSING + CONTROL CIRCUIT = 6.8 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 6.8 * 1.25 = 8.5 A



LOAD SUMMARY 8 - 1속 저속형사양

*POWER SOURCE : AC 3Φ 220(208)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	0.9KW x 4P	-	
FULL LOAD CURRENT	4.7 (A)	0 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상시 : HOISTING + CONTROL CIRCUIT = 6.7 A

*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용

NOMAL 전류값 * K = 6.7 * 1.25 = 8.375 A

*POWER SOURCE : AC 3Φ 380(440)V

OBJECT	HOISTING	TRAVERSING	CONTROL CIRCUIT
MOTOR OUTPUT	0.9KW x 4P	-	
FULL LOAD CURRENT	2.6 (A)	0 (A)	2 (A)

*크레인 하중상태를 HOIST의 정격 LOAD의 100(%)를 사용했을때를 기준으로 작성하였음.

*** NOMAL 전류값 ***

권상시 : HOISTING + CONTROL CIRCUIT = 4.6 A




*** PEAK 전류값 ***

K= NAMAL 전류치가 50A미만일때 1.25, 50A이상일때 1.1적용





NOMAL 전류값 * K = 4.6 * 1.25 = 5.75 A






ROTATING MACHINE

-  SYNCHRONOUS GENERATOR, 3-PHASE
-  AC INDUCTION MOTOR, 3-PHASE
- * N : NORMAL DUTY
- * S : STAND-BY
-  DC MOTOR



LIGHTNING ARRESTERS

-  LA : LIGHTNING ARRESTER
-  SA : SURGE ARRESTER
-  SS : SURGE SUPPRESSOR
-  DISCHARGE COUNTER















INSTRUMENT TRANSFORMERS




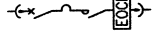
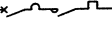
-  CURRENT TRANSFORMER
-  ZERO PHASE CURRENT TRANSFORMER
-  POTENTIAL TRANSFORMER

CIRCUIT BREAKERS






-  POWER CIRCUIT BREAKER, FIXED TYPE
- GCB : SF6 GAS CIRCUIT BREAKER
- VCB : VACUUM CIRCUIT BREAKER
- ACB : AIR CIRCUIT BREAKER
-  POWER CIRCUIT BREAKER, DRAWOUT TYPE

SWITCHES











-  DISCONNECTOR SWITCH, SINGLE THROW MANUALLY OPERATED
-  LOAD BREAK SWITCH, SINGLE THROW MANUALLY OPERATED,
-  EARTHING SWITCH, SINGLE THROW MANUALLY OPERATED
-  DISCONNECTOR SWITCH, SINGLE THROW MOTOR OPERATED
-  EARTHING SWITCH, SINGLE THROW MOTOR OPERATED
-  VACUUM CIRCUIT SWITCH
-  FUSED DISCONNECTOR SWITCH
-  FUSE-SWITCH
-  LIMIT SWITCH (MAKE CONTACT)
-  LIMIT SWITCH (BREAK CONTACT)
-  PUSH BUTTON, NORMALLY OPEN MOMENTARY CONTACT
-  PUSH BUTTON, NORMALLY CLOSED MOMENTARY CONTACT
-  PUSH BUTTON, NORMALLY OPEN PUSH TO LOCK, RELEASED BY KEY
-  MANUAL SELECTOR SWITCH (LOCKED)





-  AUX. CONTACT, NORMALLY OPEN WHEN MAIN SWITCHING DEVICE IS DE-ENERGIZED
-  AUX. CONTACT, NORMALLY CLOSED WHEN MAIN SWITCHING DEVICE IS DE-ENERGIZED
-  MAGNETIC CONTACTOR, ELECTRICALLY OPERATED
-  COMBINATION STARTER, FULL VOLTAGE, NON-REVERSING, DRAWOUT TYPE, WITH ELECTRICALLY OPERATED CONTACTORS, WITH MAGNETIC MOTOR CIRCUIT BREAKER, BUILT IN ELECTRONIC OVER-CURRENT RELAY WITH ADJUSTABLE TRIP RATING
-  COMBINATION STARTER, FULL VOLTAGE, NON-REVERSING, FIXED TYPE, WITH ELECTRICALLY OPERATED CONTACTORS, WITH MAGNETIC MOTOR CIRCUIT BREAKER, BUILT IN THERMAL OVER-CURRENT RELAY WITH ADJUSTABLE TRIP RATING


GRAPHIC SYMBOLS

-  GENERAL OPERATING COIL
-  CAPACITOR
-  CAPACITOR VOLTAGE TRANSFORMER(CVT)
-  RESISTOR
-  DIODE

CONTACTORS AND STARTERS

-  CONTROLLED RECTIFIER
-  DC-DC CONVERTER
-  RECTIFIER, BATTERY CHARGER
-  DC-AC INVERTER
-  BATTERY BANK
-  ELECTRIC HEATER, INDICATE 1* OR 3* AND KW RATING, UNLESS OTHERWISE SPECIFIED, TO BE REGARDED AS 1*.
-  EARTHING CONNECTION
-  DISCONNECTION LINK
-  CROSSING OF CONDUCTORS NOT CONNECTED
-  JUNCTION OF CONDUCTORS OR WIRES

-  BUS DUCT
- SPB : SEGREGATED PHASE BUS DUCT
- IPB : ISOLATED PHASE BUS DUCT
-  CABLE HEAD AND CABLE CONNECTION
-  AMMETER SWITCH
-  VOLTMETER SWITCH

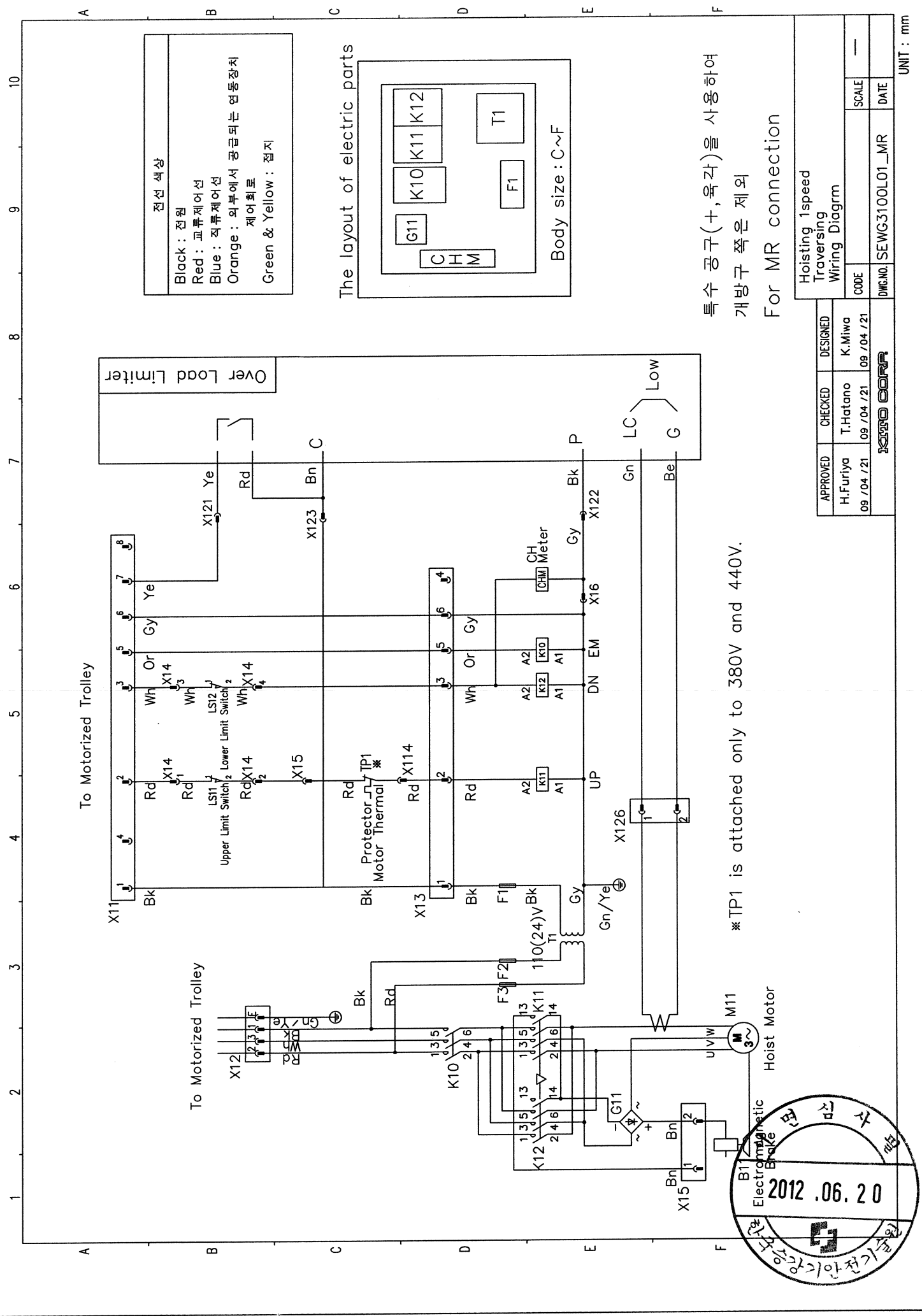
-  SIGNAL LAMP
- * R = RED
- * G = GREEN
- * W = WHITE
- * C = CYAN

- Y = YELLOW
- B = BLUE
- A = AMBER

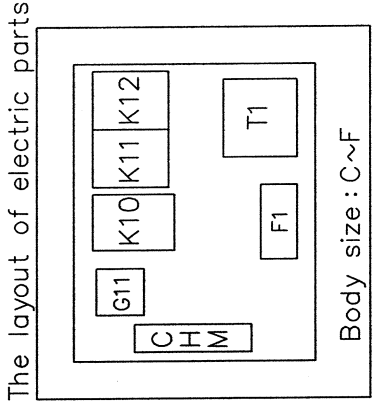
SYMBOL LIST

APPROVED	CHECKED	DESIGNED
KOTO CORP		
CODE	SYMBOL LIST	SCALE
DATE	DATE	DATE





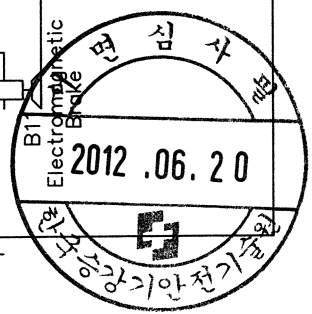
전선 색상
 Black : 전원
 Red : 교류제어선
 Blue : 직류제어선
 Orange : 외부에서 공급되는 연동장치 제어회로
 Green & Yellow : 접지



특수 공구(+, 육각)를 사용하여
 개방구 쪽은 제외
 For MR connection

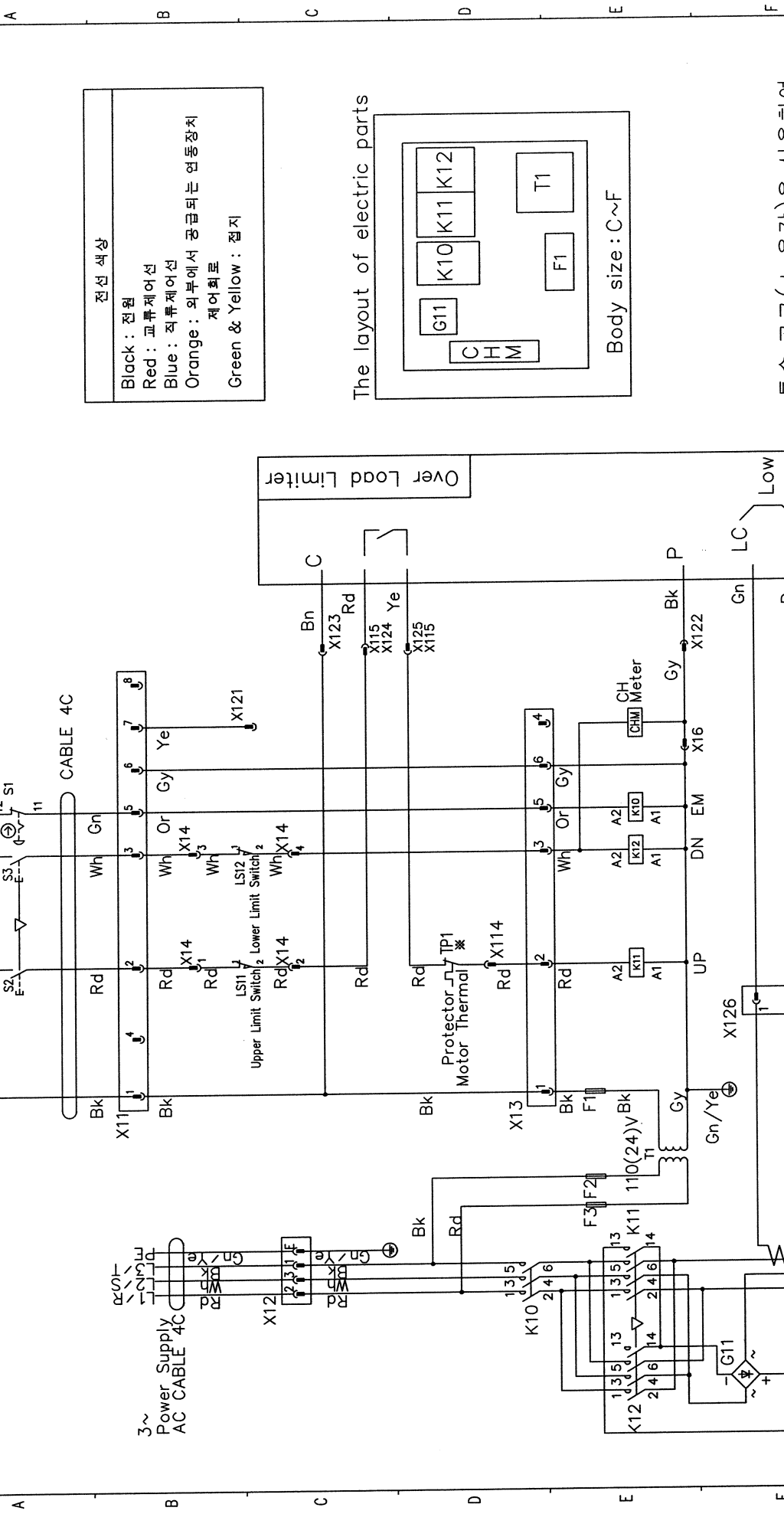
Hoisting 1speed Traversing Wiring Diagram	
APPROVED	DESIGNED
H.Furiya 09./04./21	T.Hatano 09./04./21
KOTO CORP	
CODE	SCALE
DWG.NO. SEWG3100L01_MR	DATE

* TP1 is attached only to 380V and 440V.

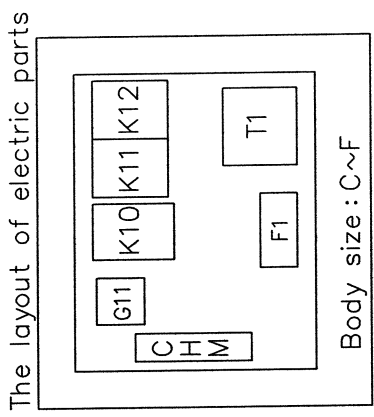


UNIT : mm

10 9 8 7 6 5 4 3 2 1



전선 색상	
Black	: 전원
Red	: 교류제어선
Blue	: 직류제어선
Orange	: 외부에서 공급되는 연동장치 제어회로
Green & Yellow	: 접지



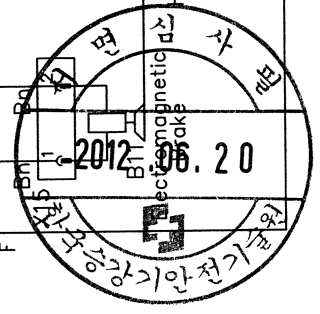
특수 공구(+, 육각)을 사용하여
개방구 쪽은 제외

* TP1 is attached only to 380V and 440V.

APPROVED	CHECKED	DESIGNED
H.Furiya 09 / 04 / 21	T.Hatano 09 / 04 / 21	K.Miwa 09 / 04 / 21

CODE	SCALE	DATE
SEWC3100L01	—	—

UNIT : mm



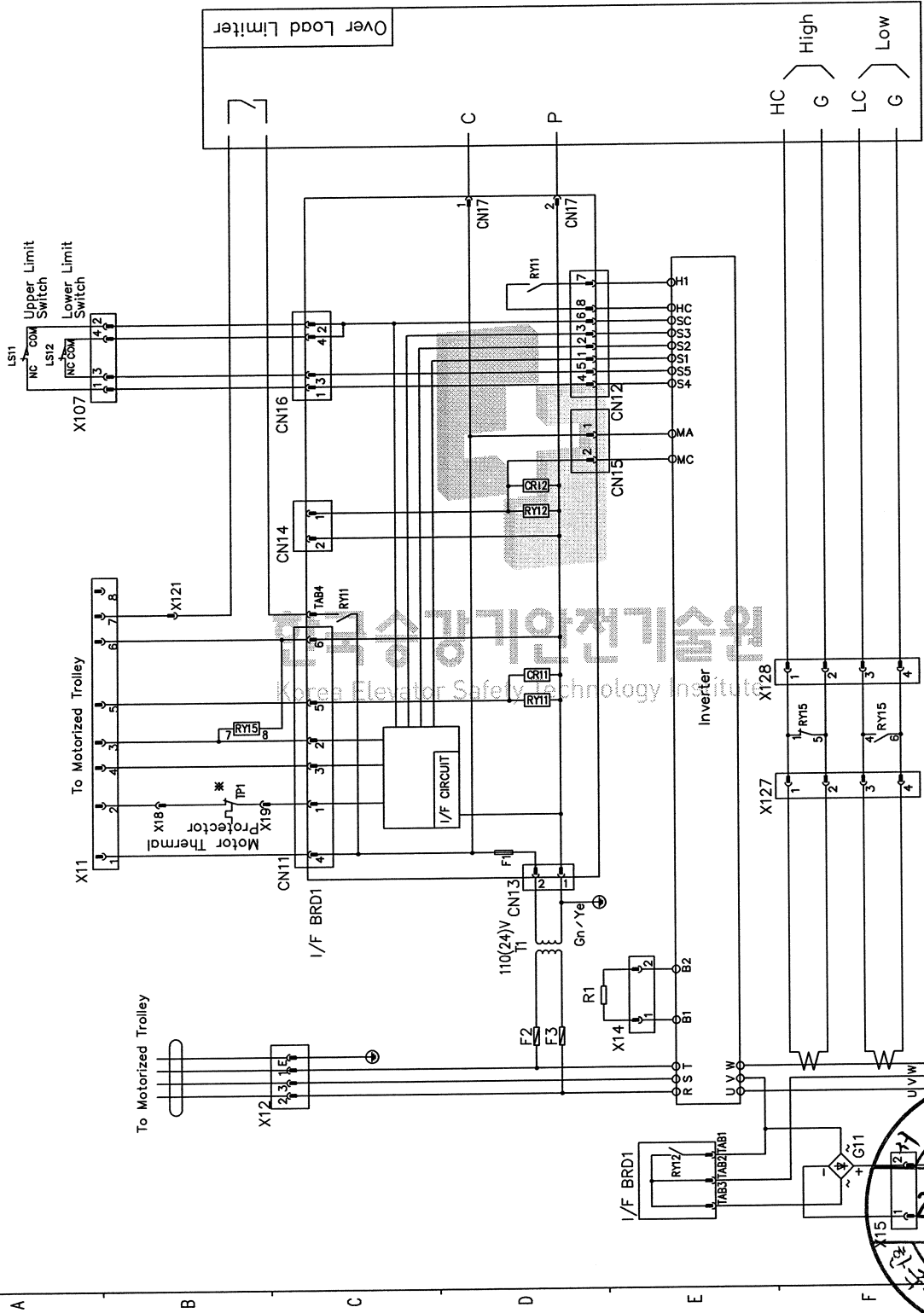
10 9 8 7 6 5 4 3 2 1

A B C D E F

전선 색상
 Black : 전철
 Red : 교류제어선
 Blue : 직류제어선
 Orange : 외부에서 공급되는 연동장치 제어회로
 Green & Yellow : 접지

The layout of electric parts
 Body size : C

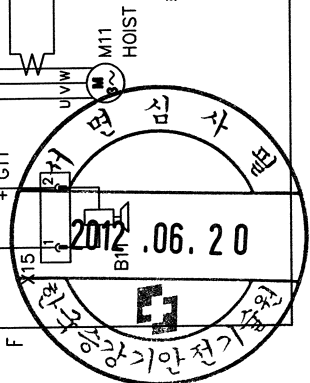
Body size : D~F



APPROVED		CHECKED	DESIGNED
H. Furiya		H. Hatano	K. Miwa
09 / 04 / 21		09 / 04 / 21	09 / 04 / 21
KOTO CORP			
DWG. NO.		SEWG3D00L01_MR	
SCALE		DATE	
—		—	

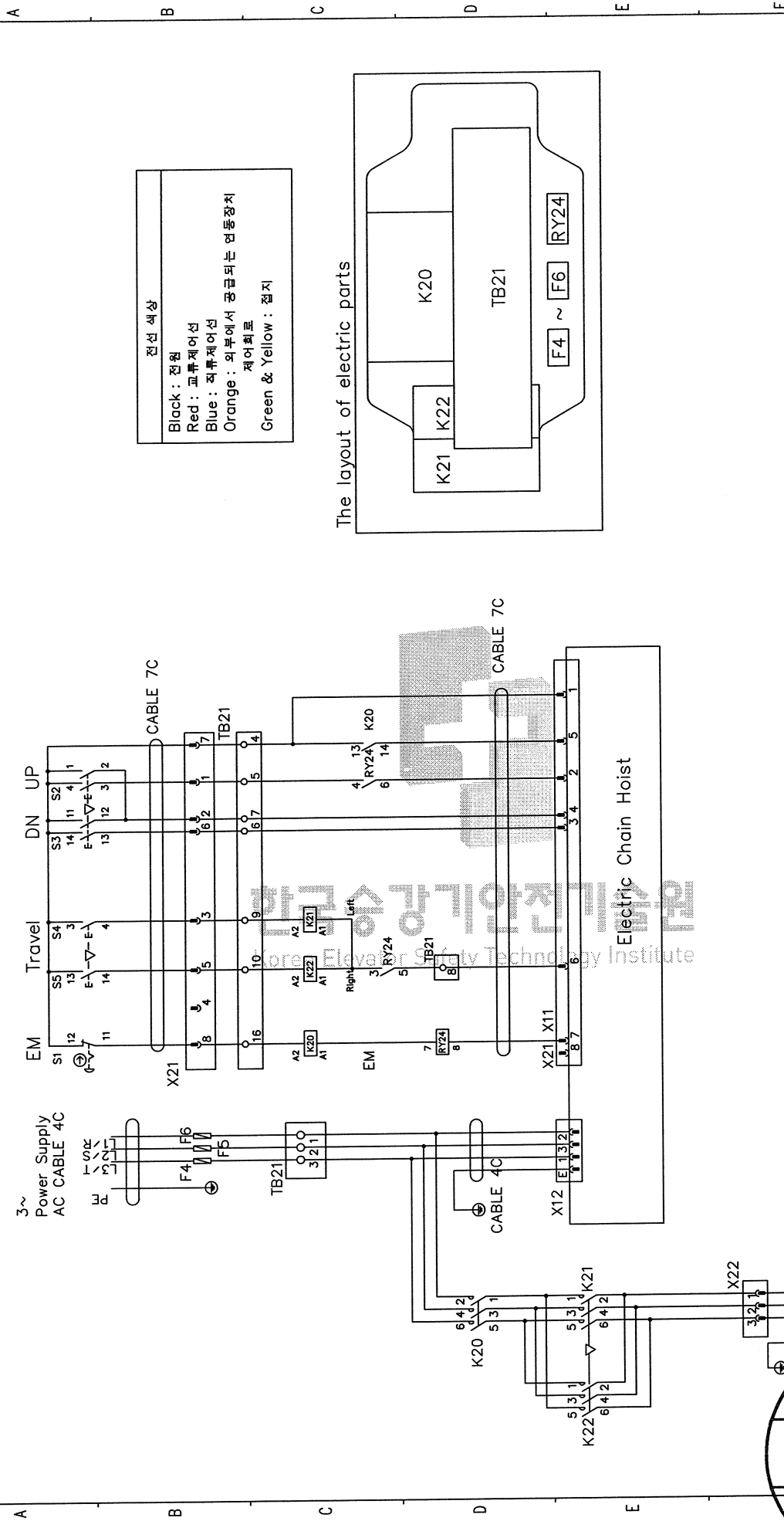
Hoisting 2speed
 Traversing
 Wiring Diagram

* TP1 is attached only to 380V and 440V.



UNIT : mm

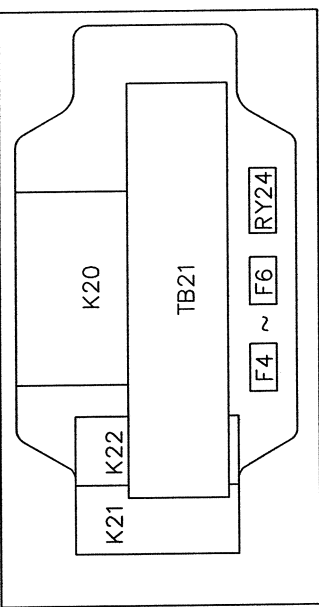
10 9 8 7 6 5 4 3 2 1



전선 색상

Black : 전원
Red : 교류제어선
Blue : 직류제어선
Orange : 외부에서 공급되는 연동장치 제어회로
Green & Yellow : 접지

The layout of electric parts



특수 공구 (+, 육각)을 사용하여
개방구 쪽은 제외

APPROVED		CHECKED		DESIGNED	
H.Furiya		H.Hatano		K.Miwa	
09 / 04 / 21		09 / 04 / 21		09 / 04 / 21	
KOTO CORP					
Traversing 1speed Wiring Diagram				CODE	SCALE
DWG.NO. SEWG3DD0L01				DATE	—

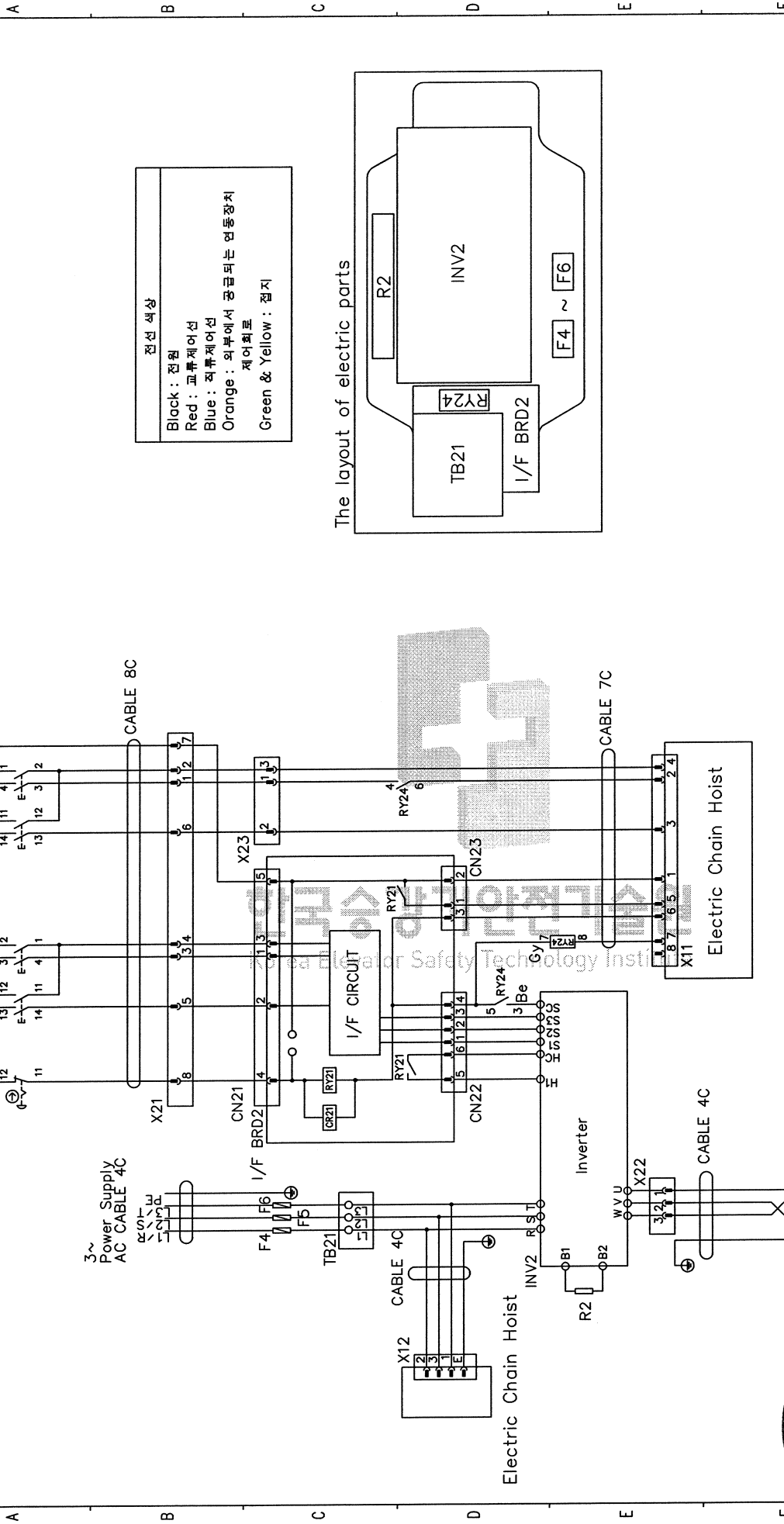
UNIT : mm

2012 .06. 20

0.4KW
M21
Traversing

Motor Assy

10 9 8 7 6 5 4 3 2 1



전선 색상

Black	: 전원
Red	: 교류제어선
Blue	: 직류제어선
Orange	: 외부에서 공급되는 연동장치 제어회로
Green & Yellow	: 접지

The layout of electric parts

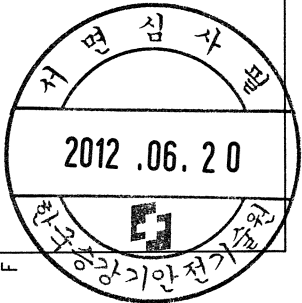
특수 공구(+, 육각)을 사용하여
개방구 쪽은 제외

Traversing 2speed
Wiring Diagram

APPROVED	CHECKED	DESIGNED
H.Furiya 09 / 04 / 21	H.Hatano 09 / 04 / 21	K.Miwa 09 / 04 / 21

CODE	SCALE	DATE
DMGNO. SEWG3DD0L01	---	---

UNIT : mm



CABLE 구성도 및 사양 - 권상 용량 0.9kW , 1.8kW

CABLE SPECIFICATION FOR ER2M

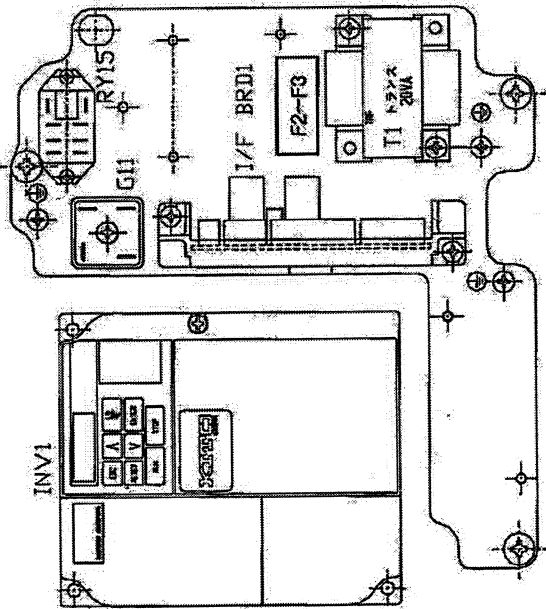
NO	ITEM	TYPE	ER2M10	
			SIZE	
①	Power Line	VCT	3.5sq x 4C	
②	Push Button Switch	VCT	1.25sq x 8C	
③	Loas Limit	VCT	0.75sq x 8C	
④	Power Line for ER	VCT	2sq x 4C	
⑤	Control Line for ER	VCT	1.25sq x 6C	
⑥	Traversing Motor With Earth	VCT	1.25sq x 4C	

(3Φ 220(208)V / 380V / 440V 60Hz)

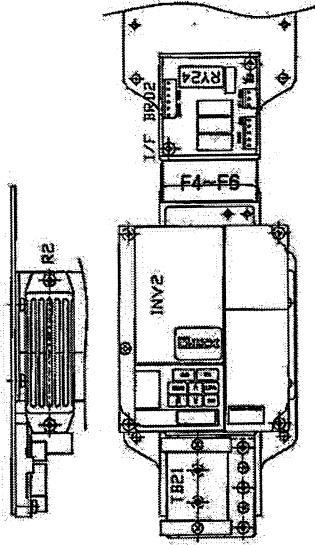


호이스트 CONTROL BOX 배치도

HOISTING CONTROL BOX

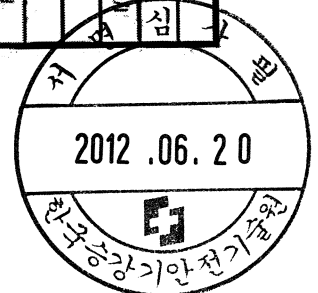


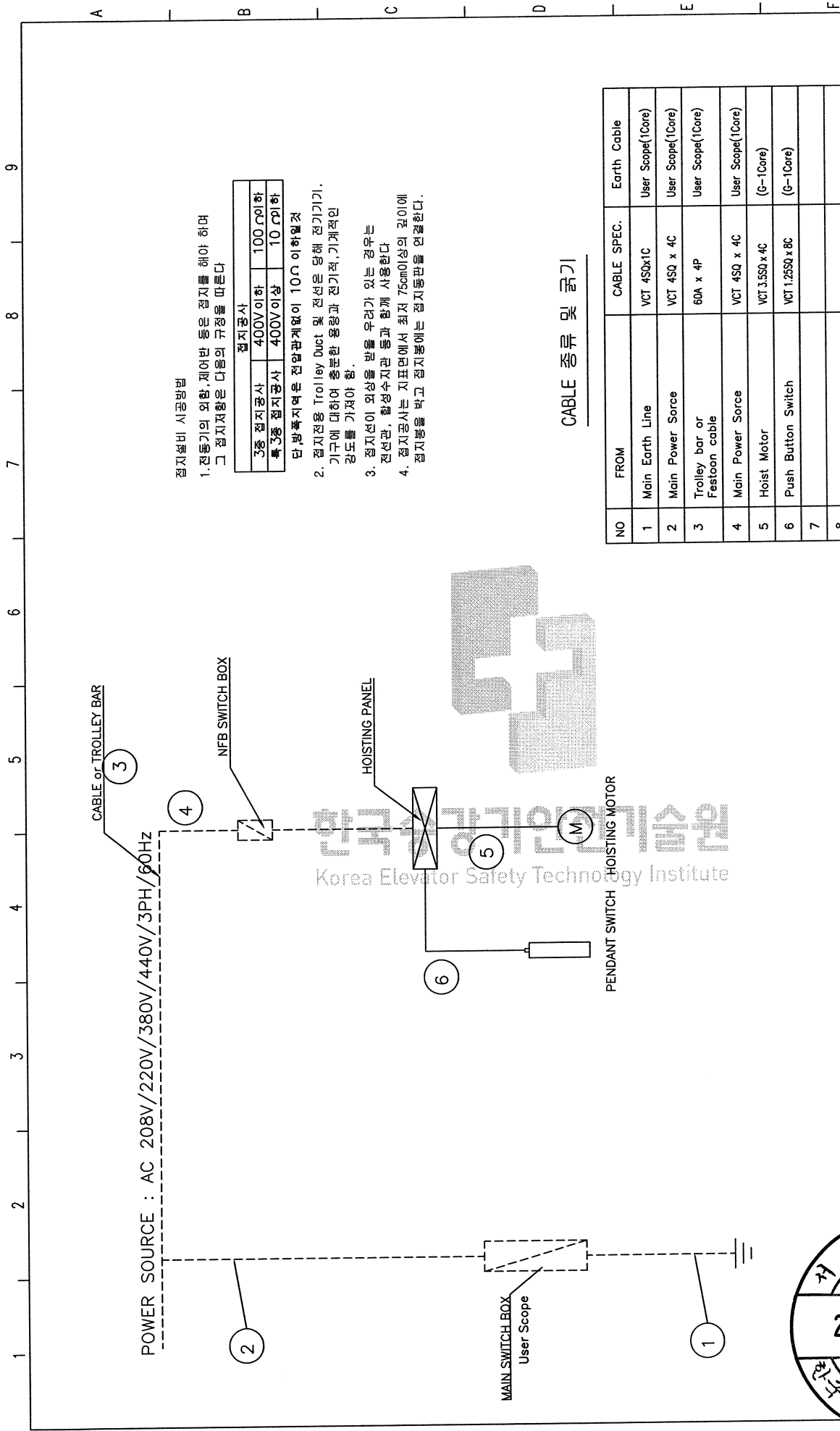
TRAVERSING CONTROL BOX



ENCLOSURE : HOIST BODY - IP55
PUSH BUTTON - IP65

MARK	DESCRIPTION	TYPE OF MODEL			QTY	MAKER	REMARKS
		220V	380V	440V			
INV1	INVERTER	V1000	V1000	V1000	1	YASKAWA	UP/DOWN
T1	TRANSFORMER	220V/24V(110V)20VA	380V/24V(110V)20VA	440V/24V(110V)20VA	1	KITO	CONTROL CIRCUIT
G11	BRIDGE DIODE	S15VB60	S15VB60	S15VB60	1	SHINDENGEN	
1/F BRD1	INTERFACE BOARD	10~15A	10~15A	10~15A	1	KITO	
F2-F3	GLASS FUSE	10A	10A	10A	2	FUJI	
F4-F6	GLASS FUSE	30A	30A	30A	3	FUJI	
RY15	RELAY	110V	110V	110V	1	OMRON	HIGH/LOW
INV2	INVERTER	V1000	V1000	V1000	1	YASKAWA	RIGHT/LEFT
1/F BRD2	INTERFACE BOARD	10~15A	10~15A	10~15A	1	KITO	
RY24	RELAY	110V	110V	110V	1	OMRON	EMERGENCY STOP
TB21	TERMINAL BOARD 21	10~15A	10~15A	10~15A	1	KITO	





접지설비 시공방법

- 전동기의 외함, 제어반 등은 접지를 해야 하며 그 접지 저항은 다음의 규정을 따른다

접지공사		
3중 접지공사	400V이하	100Ω이하
특3중 접지공사	400V이상	10Ω이하

단, 방폭지역은 전압관계없이 10Ω 이하일것

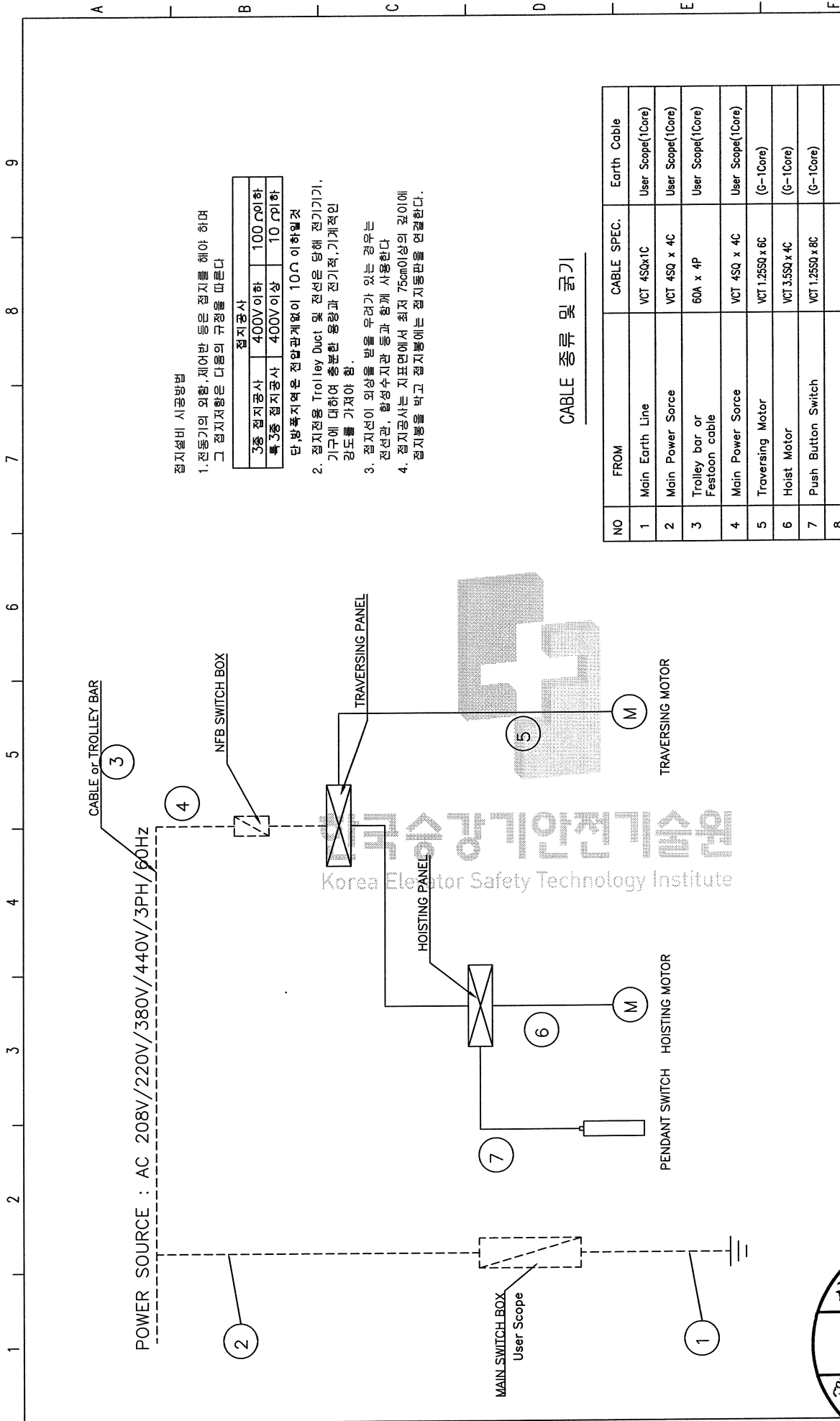
- 접지전용 Trolley Duct 및 전선은 당해 전기기기, 기구에 대하여 충분한 용량과 전기적, 기계적인 강도를 가져야 함.
- 접지선이 외상을 받을 우려가 있는 경우는 전선관, 합성수지관 등과 함께 사용한다
- 접지공사는 지표면에서 최저 75cm이상의 깊이에 접지봉을 박고 접지봉에는 접지동반을 연결한다.

CABLE 종류 및 굵기

NO	FROM	CABLE SPEC.	Earth Cable
1	Main Earth Line	VCT 4SQx1C	User Scope(1Core)
2	Main Power Sorce	VCT 4SQ x 4C	User Scope(1Core)
3	Trolley bar or Festoon cable	60A x 4P	User Scope(1Core)
4	Main Power Sorce	VCT 4SQ x 4C	User Scope(1Core)
5	Hoist Motor	VCT 3.5SQ x 4C	(G-1Core)
6	Push Button Switch	VCT 1.25SQ x 8C	(G-1Core)
7			
8			

REV.	QTY	CONTENTS	DATE	DRAWN	APPROVED	APPROVED	CHECKED	DESIGNED	DRAWN	TITLE
										1t MOTORIZED-2점식 케이블 구성도 및 접지계통도
										MDL. 942513
										SCALE NOT
										REV. 0
										UNIT : mm





접지설비 시공방법

- 전동기의 외함, 제어반 등은 접지를 해야 하며 그 접지 저항은 다음의 규정을 따른다
- 접지선용 Trolley Duct 및 전선은 당해 전기기기, 기구에 대하여 충분한 용량과 전기적, 기계적인 강도를 가져야 함.
- 접지선이 외상을 받을 우려가 있는 경우는 전선관, 합성수지관 등과 함께 사용한다
- 접지공사는 지표면에서 최저 75cm이상의 깊이에 접지봉을 박고 접지봉에는 접지등판을 연결한다.

접지공사	
3중 접지공사	400V 이하 100Ω 이하
복3중 접지공사	400V 이상 10Ω 이하

단, 반복지역은 전압관계없이 10Ω 이하일 것

CABLE 종류 및 굵기

NO	FROM	CABLE SPEC.	Earth Cable
1	Main Earth Line	VCT 45Qx1C	User Scope(1Core)
2	Main Power Source	VCT 45Q x 4C	User Scope(1Core)
3	Trolley bar or Festoon cable	60A x 4P	User Scope(1Core)
4	Main Power Source	VCT 45Q x 4C	User Scope(1Core)
5	Traversing Motor	VCT 1.25SQ x 6C	(6-1Core)
6	Hoist Motor	VCT 3.5SQ x 4C	(6-1Core)
7	Push Button Switch	VCT 1.25SQ x 8C	(6-1Core)
8			

REV.	QTY	CONTENTS	DATE	DRAWN	APPROVED	CHECKED	DESIGNED	DRAWN	TITLE
									1t MOTORIZED-4점식 케이블 구성도 및 접지계통도
									MDL: 942513
									DWG. NO. 3NNU942513
									SCALE NOT
									REV. 0



Date: 2009/04/14

Certificate of Compliance

We certify that the ER2 protection degrees conform to the IP rating as follows:

Hoist body - IP55 based on JIS C 4034-5, "Rotating electrical machines – Part5: Classification of degrees of protection provided by enclosures of rotating electrical machines (IP code)".

Push button - IP65 based on JIS C 0920, "Tests to prove protection against ingress of water and degrees of protection against ingress of solid objects for electrical equipment".

Technical Control Group

Test Certificate

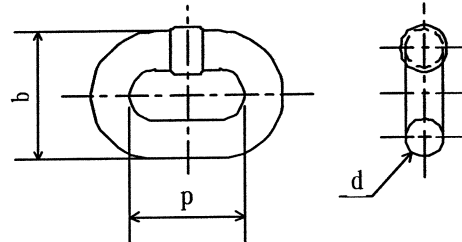
Messrs.

Commodity: NC Load Chain

Code: KER077

Lot No.: -

Quantity: - line(s)



1. Material: Manganese Alloy Steel

2. Dimensions

	d	p	b
Specified	7.7mm ±0.3	21.4mm $\begin{matrix} +0.46 \\ 0 \end{matrix}$	Max. 27.0mm
Result	Good	Good	Good

3. Breaking test

	Breaking load	Total ultimate elongation
Specified	Min. 75 (kN)	Min. 10 (%)
Result	Good	Good

Korea Elevator Safety Technology Institute

4. Manufacturing Proof force test (Test load: 46.6 kN)

	Permanent elongation
Specified	0.25 (%)
Result	Good

General judgment: Satisfactory



2000 Tsuijjarai, Showa-cho,
Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

K. Kishimoto (Manager)

Messrs. _____

Motor Test Report for Electric Chain Hoist

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. : -

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ	0.9kW	4P	60%ED	220V	60Hz

Full load characteristics

Voltage Frequency		220V 60Hz
Load	%	100
Current	A	4.7
Speed	rpm	1660

Insulation class E

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



2000 Tsuijirai, Showa-cho,
Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

M. Ogihara

(Manager)

Messrs. _____

Motor Test Report for Electric Chain Hoist

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. : -

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ	0.9kW	4P	40/20%ED	220V	Speed Control by Inverter

Full load characteristics

Voltage	Frequency	220V	Speed Control by Inverter
Load	%	100	
Current	A	5.7	
Speed	rpm	~	

Insulation class E

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



2000 Tsuijirai, Showa-cho,
Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

M. Ogihara (Manager)

Messrs. _____

Motor Test Report for Electric Chain Hoist

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. :

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ	0.9kW	4P	60%ED	380 - 440V	60Hz

Full load characteristics

Voltage	Frequency	380 - 440V	60Hz
Load	%	100	
Current	A	2.6	
Speed	rpm	1640	

Insulation class B

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



2000 Tsuijirai, Showa-cho,
Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

(Manager)

K. Kishimoto

Messrs. _____

Motor Test Report for Electric Chain Hoist

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. :

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ	0.9kW	4P	60%ED	380 - 440V	Speed Control by Inverter

Full load characteristics

Voltage	Frequency	380 - 440V	Speed Control by Inverter
Load	%	100	
Current	A	3.6	
Speed	rpm	~	

Insulation class B

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



2000 Tsuijiarai, Showa-cho,
Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

(Manager)

K. Kishimoto

Messrs. _____

Motor Test Report for Electric Chain Hoist

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. : -

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ	1.8kW	4P	60%ED	220V	60Hz

Full load characteristics

Voltage	Frequency	220V	60Hz
Load	%	100	
Current	A	8.4	
Speed	rpm	1620	

Insulation class E

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



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Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

M. Ogihara (Manager)

Messrs. _____

Motor Test Report for Electric Chain Hoist

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. : -

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ	1.8kW	4P	40/20%ED	220V	Speed Control by Inverter

Full load characteristics

Voltage Frequency		220V	Speed Control by Inverter
Load	%	100	
Current	A	11.2	
Speed	rpm	~	

Insulation class E

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



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Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

M. Ogihara (Manager)

Certificate No.: MM070011e

Date of Issue: 2008/03/21

Messrs. _____

Motor Test Report for Electric Chain Hoist

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. :

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ	1.8kW	4P	60%ED	380 - 440V	60Hz

Full load characteristics

Voltage	Frequency	380 - 440V	60Hz
Load	%	100	
Current	A	4.6	
Speed	rpm	1610	

Insulation class B

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



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Quality Assurance Group
Quality Assurance Department
Development & Technology Division

(Manager)

K. Kishimoto

Messrs. _____

Motor Test Report for Electric Chain Hoist

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. :

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ	1.8kW	4P	60%ED	380 - 440V	Speed Control by Inverter

Full load characteristics

Voltage	Frequency	380 - 440V	Speed Control by Inverter
Load	%	100	
Current	A	5.1	
Speed	rpm	~	

Insulation class B

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



2000 Tsuijarai, Showa-cho,
Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

(Manager)

K. Kishimoto

Messrs. _____

Motor Test Report for Electric Trolley

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. : -

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ-T	0.4kW	4P	40%ED	220V	60Hz

Full load characteristics

Voltage Frequency		220V 60Hz
Load	%	100
Current	A	3.0
Speed	rpm	1685

Insulation class E

The above characteristics are obtained from calculation where the motor is assembled with an electric trolley and the trolley is subjected to full load



2000 Tsuijirai, Showa-cho,
Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

M. Ogihara

(Manager)

Messrs. _____

Motor Test Report for Electric Trolley

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. : -

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ-T	0.4kW	4P	27/13%ED	220V	Speed Control by Inverter

Full load characteristics

Voltage	Frequency	220V	Speed Control by Inverter
Load	%	100	
Current	A	3.0	
Speed	rpm	~	

Insulation class E

The above characteristics are obtained from calculation where the motor is assembled with an electric trolley and the trolley is subjected to full load



2000 Tsuijirai, Showa-cho,
Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

M. Ogihara (Manager)

Messrs. _____

Motor Test Report for End Carriage

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. :

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ-T	0.4kW	4P	40%ED	380 - 440V	60Hz

Full load characteristics

Voltage	Frequency	380 - 440V 60Hz
Load	%	100
Current	A	2.2
Speed	rpm	1670

Insulation class B

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



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Nakakoma-gun, Yamanashi, JAPAN

Quality Assurance Group
Quality Assurance Department
Development & Technology Division

(Manager)

K. Kishimoto

Messrs. _____

Motor Test Report for End Carriage

Motor type : Three phase squirrel cage type induction motor.

Manufacturer : Yasukawa Electric Mfg. Co.

Production No. :

Rating

Model	Output	Pole	Intermittent Rating	Voltage	Frequency
IBQ-T	0.4kW	4P	40%ED	380 - 440V	Speed Control by Inverter

Full load characteristics

Voltage	Frequency	220 - 230V	Speed Control by Inverter
Load	%	100	
Current	A	2.5	
Speed	rpm	~	

Insulation class B

The above characteristics are obtained from calculation where the motor is assembled with an electric chain hoist and the hoist is subjected to full load



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